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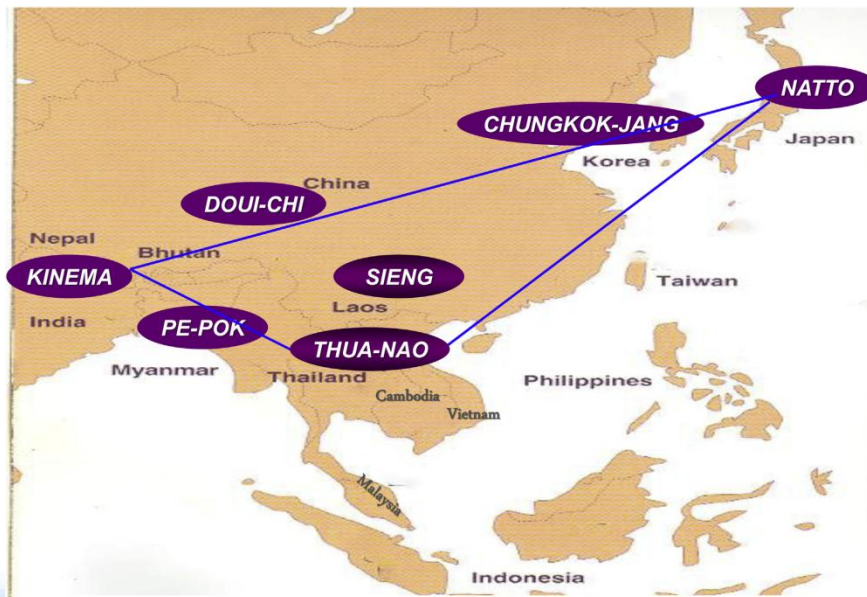
Data Reduction and Uncertainty Propagation

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Natto (Fermented Soya Beans, *Bekang* in Mizo)



Jyoti Prakash Tamang,
J. Ethnic Foods 2 (2015) 8



More Details about Bekang, Natto etc.

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Review article

Naturally fermented ethnic soybean foods of India

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Open access article



Mathematical Details about Uncertainty Propagation

This presentation introduces several uncertainty propagation formulae **without their proofs**. See my recent article for their proofs:

<http://www-nds.iaea.org/nrdc/india/ws2017/aizawl2017/otuka.pdf>

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Uncertainty propagation in activation cross section measurements

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$\int_{-\infty}^{+\infty} dx p(x_1, x_2, \dots) = 1$, where $dx = dx_1 dx_2 \dots$. The mean value (best estimate) x_{k0} , covariance $\text{Cov}(x_k, x_l)$, correlation coefficient $\text{Cor}(x_k, x_l)$, variance $\text{Var}(x_k)$, and standard deviation Δx_k are defined by

$$x_{k0} = \int dx x_k p(x_1, x_2, \dots), \quad (1)$$

$$\text{Cov}(x_k, x_l) = \int dx (x_k - x_{k0})(x_l - x_{l0}) p(x_1, x_2, \dots), \quad (2)$$

$$\text{Cor}(x_k, x_l) = \text{Cov}(x_k, x_l) / (\Delta x_k \Delta x_l), \quad (3)$$

$$\text{Var}(x_k) = \int dx (x_k - x_{k0})^2 p(x_1, x_2, \dots) = \text{Cov}(x_k, x_k), \quad (4)$$

$$\Delta x_k = \sqrt{\text{Var}(x_k)}, \quad (5)$$

respectively. By definition, $0 \leq \text{Cor}(x_k, x_l) \leq 1$ and especially =1 when $k=l$. In nuclear data, one standard deviation of the parameter is usually treated as its *uncertainty*.¹ If x_1 is independent from the other parameters, we can decompose the probability distribution as

$$p(x_1, x_2, x_3, \dots) = P(x_1) Q(x_2, x_3, \dots), \quad (6)$$

and $\text{Cov}(x_k, x_l) = 0$ ($k \neq l$) according to the definition of the covariance.

If a set of quantities of interest $\{y_i\}$ are related to the parameters $\{x_k\}$ by $y_i = y_i(x_1, x_2, \dots)$ and the relation can be linearized by expansion around the mean values of the parameters as

$$y_i = y_{i0} + \sum_k a_{ik} (x_k - x_{k0}) \quad (7)$$

with $y_{i0} = y_i(x_{10}, x_{20}, \dots)$ and $a_{ik} = (\partial y_i / \partial x_k)_{x_k=x_{k0}}$ (sensitivity coefficient), the variance and covariance of x_k are propagated to those of y_i by

$$\text{Var}(y_i) = \text{Var}\left(\sum_k a_{ik} x_k\right) = \sum_k a_{ik}^2 \text{Var}(x_k) + 2 \sum_{k>l} a_{ik} \text{Cov}(x_k, x_l) a_{il}, \quad (8)$$

$$\text{Cov}(y_i, y_j) = \text{Cov}\left(\sum_k a_{ik} x_k, \sum_l a_{jl} x_l\right) = \sum_k \sum_l a_{ik} \text{Cov}(x_k, x_l) a_{jl}. \quad (9)$$

Usually not all combinations of x_k and x_l have correlation but correlate each other within their n subsets such as $(x_1, x_2, \dots, x_{M1}), (x_{M1+1}, \dots, x_{M2}), \dots$. In such a case, the covariance terms in Eqs. (13) and (14) can be decomposed to

$$\sum_{k>l} g_{ik} \text{cov}(x_k, x_l) g_{il} = \sum_{i=1}^n \sum_{k=M_{i-1}+1}^{M_i} \sum_{l=k+1}^{M_i} g_{ik} \text{cov}(x_k, x_l) g_{il}, \quad (15)$$

$$\sum_{k,l} g_{ik} \text{cov}(x_k, x_l) g_{il} = \sum_{i=1}^n \sum_{k,l=M_{i-1}+1}^{M_i} g_{ik} \text{cov}(x_k, x_l) g_{il} \quad (16)$$

with $M_0 = 0$. For example, we expect that the number of counts C_i (always independent from other parameters), number of atoms in the samples per area n_i , and number of the incident particles Φ_i acting as six parameters $\{x_i\}$ ($i=1,6$) describing the cross sections $\sigma_i = C_i / (n_i \Phi_i)$ ($i=1,2$) has the following fractional covariances:

$$\begin{pmatrix} \text{var}(C_1) & & & & & \\ 0 & \text{var}(C_2) & & & & \\ 0 & 0 & \text{var}(n_1) & & & \\ 0 & 0 & \text{cov}(n_1, n_2) & \text{var}(n_2) & & \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} \quad (17)$$

if the uncertainty in Φ_i is negligible.

When y_i cannot be expressed by Eq. (10) and there is no correlation in parameters $\{x_k\}$, Eq. (8) can be rewritten as

$$(\Delta y_i / y_{i0})^2 = \sum_k s_{ik}^2 (\Delta x_k / x_{k0})^2, \quad (18)$$

where

$$s_{ik} = (x_{k0} / y_{i0}) (\partial y_i / \partial x_k)_{x_k=x_{k0}} = (x_{k0} / y_{i0}) a_{ik} \quad (19)$$

is the relative sensitivity coefficient. Eq. (18) shows that we should distinguish the following two statements: "Uncertainty in y_i due to the uncertainty in x_k " (i.e., $s_{ik} (\Delta x_k / x_{k0})$), and "Uncertainty in x_k " (i.e.,



Data Reduction

Nuclear reaction quantity q (e.g., cross section) is always derived from primary observables x, y, z, \dots (data reduction) by a function f :

Example: Activation cross section ($\sigma_1, \sigma_2, \dots$) may be derived from ...

- measured counting rate A_1, A_2, \dots
- detector efficiency $\varepsilon_1, \varepsilon_2, \dots$
- number of sample atoms N_1, N_2, \dots
- beam flux density ϕ_1, ϕ_2, \dots

$$\rightarrow \sigma_i = f(A_i, \varepsilon_i, N_i, \phi_i) = A_i / (\varepsilon_i \cdot N_i \cdot \phi_i)$$



Basic Data Reduction

* **Addition $z = x + y$ or subtraction $z = x - y$**

Example:

Background correction to raw count: $N' = N - B$

* **Multiplication $z = x \cdot y$ or division $z = x / y$**

Example:

Efficiency correction to raw count: $N' = N / \epsilon$

Real data reduction may be a combination of these operations,

e.g., $N' = (N - B) / \epsilon$

or more complicated, e.g., $N[1 - \exp(-\lambda t)] / \epsilon$



Data Reduction and Uncertainty Propagation

Cross sections at n energies σ_i ($i=1,n$) derived from primary observables $A_i, \varepsilon_i, N_i, \phi_i$ ($i=1,n$)

Step 1: Measurements of primary observables

Determination of means and covariances for each primary observable $\langle A_i \rangle, \Delta A_i, \langle \varepsilon_i \rangle, \Delta \varepsilon_i \dots$

Step 2: Data reduction to cross sections

$\langle A_i \rangle, \Delta A_i, \langle \varepsilon_i \rangle, \Delta \varepsilon_i \dots \rightarrow \langle \sigma_i \rangle$ and $\Delta \sigma_i$

Step 2-1: Propagation of mean value

$$\langle \sigma_i \rangle = \langle A_i \rangle / (\langle \varepsilon_i \rangle \cdot \langle N_i \rangle \cdot \langle \phi_i \rangle)$$

Step 2-2: Propagation of standard deviation

~~$$\Delta \sigma_i = \Delta A_i / (\Delta \varepsilon_i \cdot \Delta N_i \cdot \Delta \phi_i)$$~~

No!



Uncertainty Propagation (Linear Combination)

$$p = \sum_{i=1,n} a_i \cdot x_i = a_1 x_1 + a_2 x_2 + \dots \quad (x_i \text{ is a random variable}).$$

Mean:

$$\langle p \rangle = \sum_{i=1,n} a_i \langle x_i \rangle$$

Variance:

$$\begin{aligned} \text{Var}(p) &= \langle p^2 \rangle - \langle p \rangle^2 \\ &= \langle (\sum_{i=1,n} a_i x_i)^2 \rangle - \langle \sum_{i=1,n} a_i x_i \rangle^2 \\ &= \sum_{i=1,n} a_i^2 \text{Var}(x_i) + 2 \sum_{i=1,n; j=1,n; i < j} a_i a_j \text{Cov}(x_i, x_j) \\ &= \sum_{i=1,n} a_i^2 (\Delta x_i)^2 + 2 \sum_{i=1,n; j=1,n; i < j} a_i a_j \text{Cor}(x_i, x_j) \Delta x_i \Delta x_j \end{aligned}$$



Uncertainty Propagation $(x,y) \rightarrow z$ for $z=x+y$

$z=x+y$ (e.g., background subtraction $N'=N-B$)

$$\langle z \rangle = \langle x \rangle + \langle y \rangle$$

$$\text{Var}(z) = \text{Var}(x) + \text{Var}(y) + 2\text{Cov}(x,y)$$

$$(\Delta z)^2 = (\Delta x)^2 + (\Delta y)^2 + 2\text{Cor}(x,y)\Delta x\Delta y$$

If x and y are independent (i.e., $c_{xy}=0$),

$$(\Delta z)^2 = (\Delta x)^2 + (\Delta y)^2 \quad (\text{quadrature sum rule})$$



Uncertainty Propagation (x,y)→z for z=x+y

$$z=x+y$$

$$\langle z \rangle = \langle x \rangle + \langle y \rangle$$

$$\text{Var}(z) = \text{Var}(x) + \text{Var}(y) + 2\text{Cov}(x,y)$$

$$(\Delta z)^2 = (\Delta x)^2 + (\Delta y)^2 + 2 \text{Cor}(x,y)\Delta x\Delta y$$

$$= (\Delta x)^2 + (\Delta y)^2$$

(if x and y are independent, $\text{Cor}(x,y)=0$)

$$= (\Delta x)^2 + (\Delta y)^2 + 2\Delta x\Delta y = (\Delta x + \Delta y)^2$$

(if x and y are fully correlated, $\text{Cor}(x,y)=+1$)

$$= (\Delta x)^2 + (\Delta y)^2 - 2\Delta x\Delta y = (\Delta x - \Delta y)^2$$

(if x and y are fully anti-correlated, $\text{Cor}(x,y)=-1$)

Which case gives the largest and smallest uncertainties?



Uncertainty Propagation (General Function)

$p=p(x_1, x_2, \dots, x_n)$: function of n random variables x_n

1st order expansion of p around $\langle p \rangle = p(\langle x_1, \langle x_2 \rangle, \dots, \langle x_n \rangle)$:

$$p - \langle p \rangle \sim \sum_{i=1, n} (\partial p / \partial x_i)_{x_i = \langle x_i \rangle} (x_i - \langle x_i \rangle)$$

If we set $p' = p - \langle p \rangle$ and $x_i' = x_i - \langle x_i \rangle$, we obtain the linear combination

$$p' = \sum_{i=1, n} (\partial p / \partial x_i)_{x_i = \langle x_i \rangle} \cdot x_i'$$

This is a linear combination, therefore

$$\begin{aligned} \text{Var}(p) = \text{Var}(p') \sim & \sum_{i=1, n} (\partial p / \partial x_i)_{x_i = \langle x_i \rangle} \text{Var}(x_i) \\ & + 2 \sum_{i=1, n; j=1, n; i < j} (\partial p / \partial x_i)_{x_i = \langle x_i \rangle} (\partial p / \partial x_j)_{x_j = \langle x_j \rangle} \text{Cov}(x_i, x_j) \end{aligned}$$



Limitation of Linear Approximation

$p = p(x_1, x_2, \dots, x_n)$: function of n random variables x_n

1st order expansion of f around $\langle p \rangle = p(\langle x_1 \rangle, \langle x_2 \rangle, \dots, \langle x_n \rangle)$:

$$p - \langle p \rangle \sim \sum_{i=1, n} (\partial p / \partial x_i)_{x_i = \langle x_i \rangle} (x_i - \langle x_i \rangle)$$

This linear approximation is valid when $x_i - \langle x_i \rangle \ll \langle x_i \rangle$, namely valid only when the uncertainty is small enough than its mean value.



Uncertainty Propagation (General Function)

$p=p(x_1, x_2, \dots, x_n)$: function of n random variables

$$\begin{aligned} \text{Var}(p) = \text{Var}(p') \sim & \sum_{i=1, n} \left(\frac{\partial p}{\partial x_i} \right)_{x_i = \langle x_i \rangle} \text{Var}(x_i) \\ & + 2 \sum_{i=1, n; j=1, n; i < j} \left(\frac{\partial p}{\partial x_i} \right)_{x_i = \langle x_i \rangle} \left(\frac{\partial p}{\partial x_j} \right)_{x_j = \langle x_j \rangle} \text{Cov}(x_i, x_j) \end{aligned}$$

This relation can be easily extended to covariance between two functions $p=p(x_1, x_2, \dots, x_n)$, $q=q(y_1, y_2, \dots, y_m)$:

$$\text{Cov}(p, q) \sim \sum_{i=1, n; j=1, m} \left(\frac{\partial p}{\partial x_i} \right)_{x_i = \langle x_i \rangle} \left(\frac{\partial q}{\partial y_j} \right)_{y_j = \langle y_j \rangle} \text{Cov}(x_i, x_j)$$



Special Case: Product/Quotient Function

For two quantities

$$\left\{ \begin{array}{l} p = (x_{1,p} x_{2,p} \dots x_{m,p}) / (x_{m+1,p} x_{m+2,p} \dots x_{n,p}) \\ q = (x_{1,q} x_{2,q} \dots x_{m,q}) / (x_{m+1,q} x_{m+2,q} \dots x_{n,q}) \end{array} \right.$$

fractional covariance $\text{cov}(p,q) = \text{Cov}(p,q) / (p \cdot q)$ is

$$\begin{aligned} \text{cov}(p,q) &\sim \sum_{k=1,n} \text{cov}(x_{k,p}, x_{k,q}) \\ &\sim \sum_{k=1,n} \text{Cor}(x_{k,p}, x_{k,q}) (\Delta x_{k,p} / \langle x_{k,p} \rangle) (\Delta x_{k,q} / \langle x_{k,q} \rangle) \end{aligned}$$

If $p=q$,

$$\text{cov}(p,p) = \text{var}(p,p) \sim \sum_{k=1,n} (\Delta x_{k,p} / \langle x_{k,p} \rangle)^2$$

$$\text{Namely } (\Delta p / \langle p \rangle)^2 = \sum_{k=1,n} (\Delta x_{k,p} / \langle x_{k,p} \rangle)^2$$

(Quadrature Sum Rule)



Example: Activation Cross Section

Activation cross sections at two energies (σ_p and σ_q) derived from

- counts A (corrected for decay)
- by the same detector (ε) and sample (thickness N)
- under flux ϕ_p and ϕ_q :

$$\sigma_p = A_p / (\varepsilon N \phi_p) \text{ and } \sigma_q = (A_q / \varepsilon N \phi_q)$$

Fractional variance (uncertainty):

$$\text{var}(\sigma_p) = (\Delta\sigma_p / \sigma_p)^2 = (\Delta A_p / A_p)^2 + (\Delta\varepsilon_p / \varepsilon_p)^2 + (\Delta N_p / N_p)^2 + (\Delta\phi_p / \phi_p)^2$$

Fractional covariance:

$$\text{cov}(\sigma_p, \sigma_q) = (\Delta\varepsilon_p / \varepsilon_p)^2 + (\Delta N_p / N_p)^2 \quad (p \neq q)$$



Summary

- **Uncertainty propagation depends on combination of random variables**
 - linear combination (e.g., $z=x+y$)
 - non-linear combination (e.g., $z=x/y$) - Taylor expansion around mean value
 - Product/quotient combination (e.g., activation formula)
- **Quadrature sum rule for the fractional uncertainty**

The formula $(\Delta y / \langle y \rangle)^2 = \sum_{i=1,n} (\Delta x_i / \langle x_i \rangle)^2$ is applicable when

 - y is a product/quotient combination $(x_1 x_2 \dots x_m) / (x_{m+1} x_{m+2} \dots x_n)$
 - Δx_i is enough smaller than $\langle x_i \rangle$ (for 1st order approximation)



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